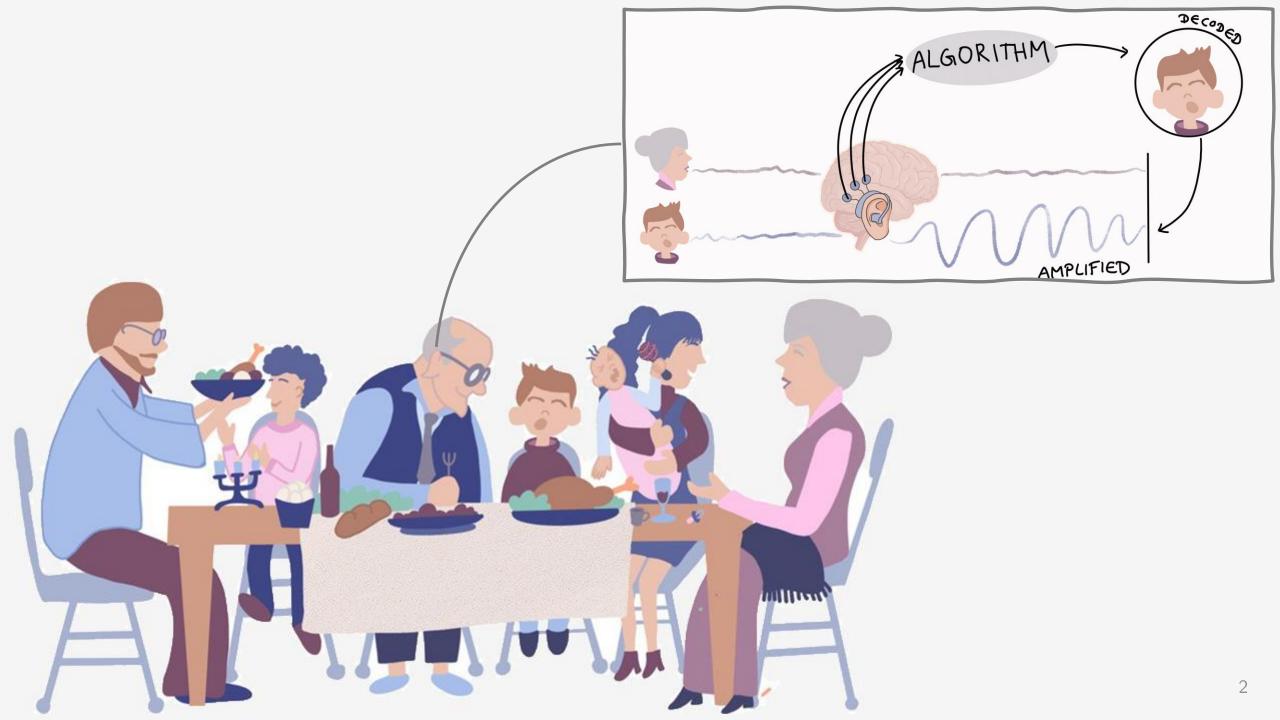
# AAD signal processing Into The Wild

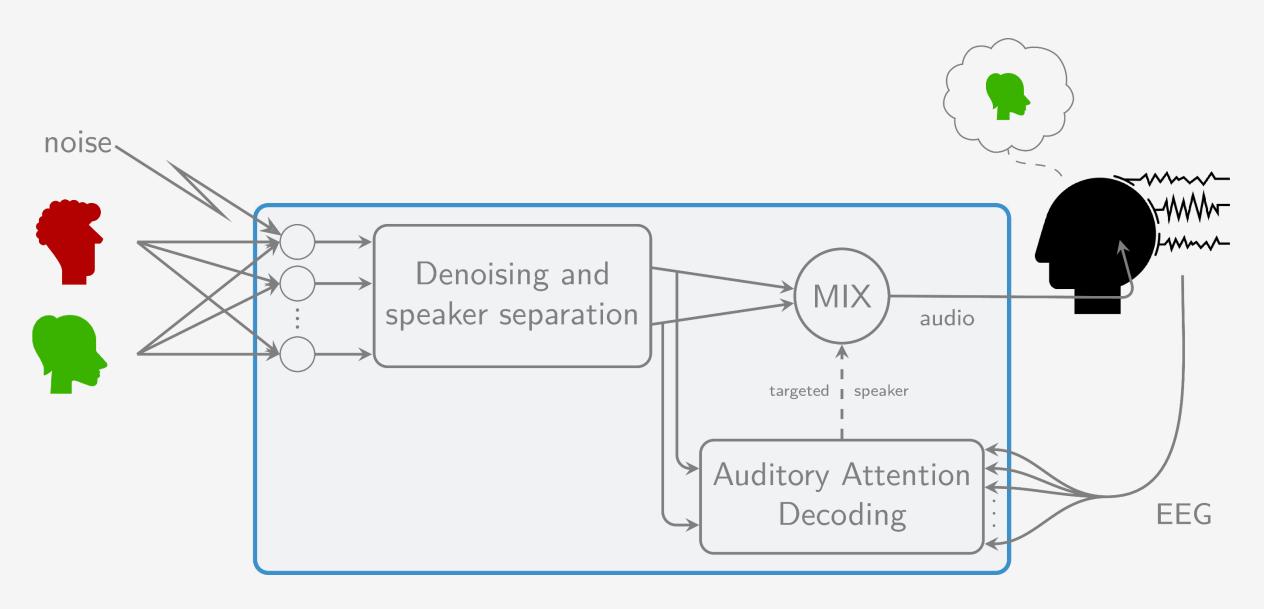




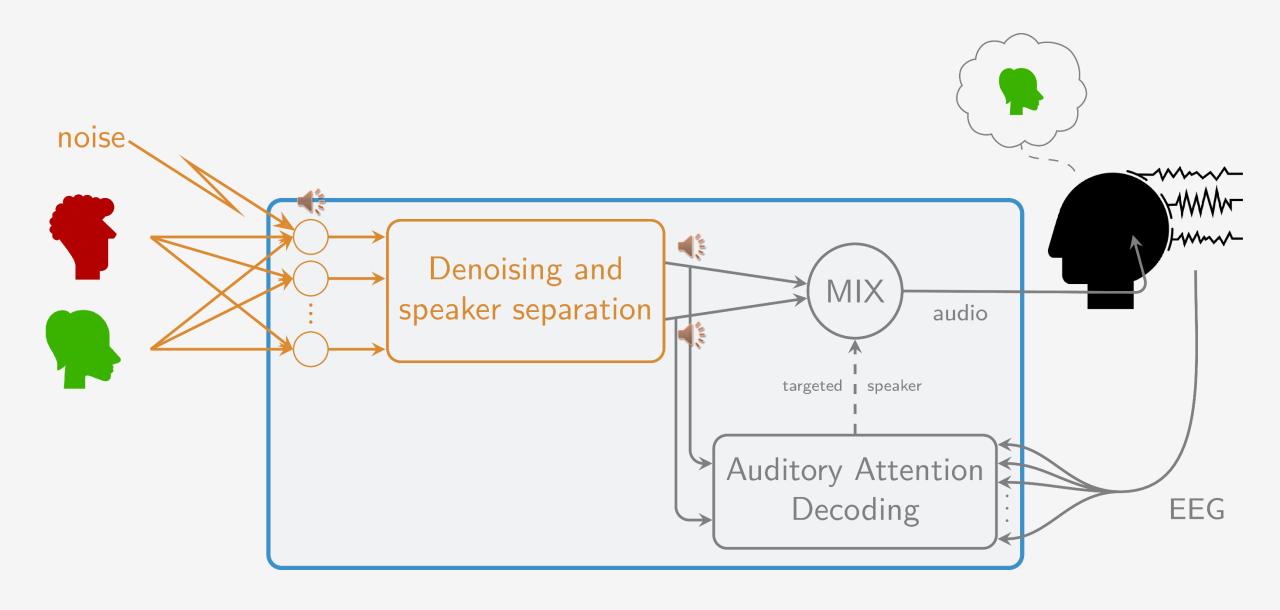


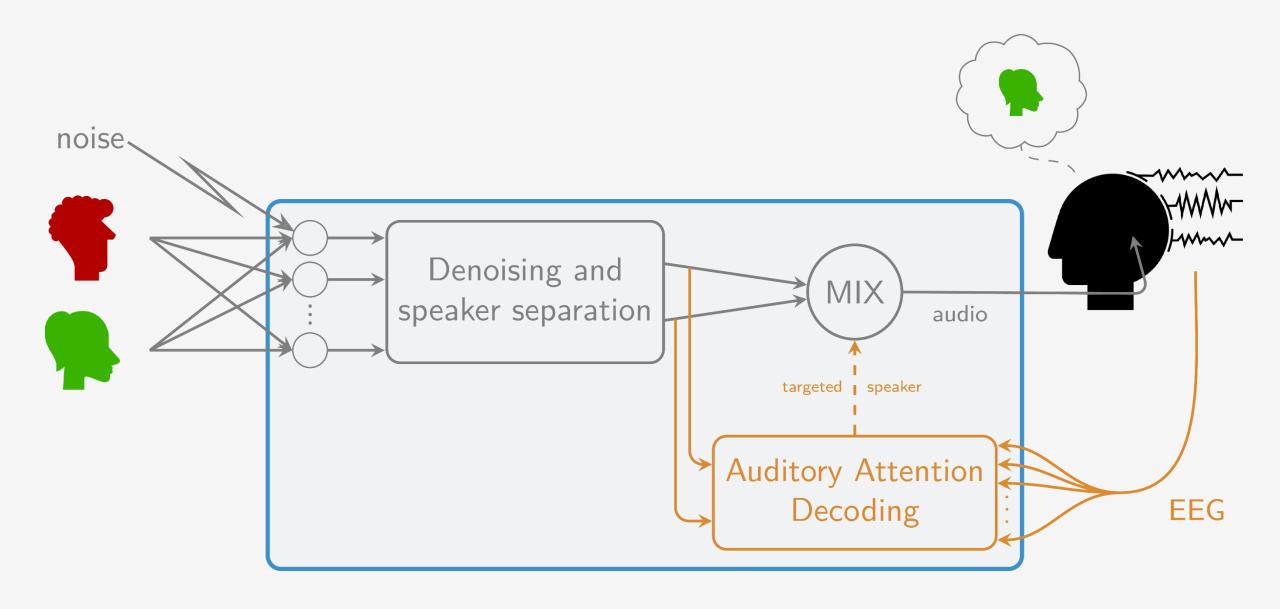


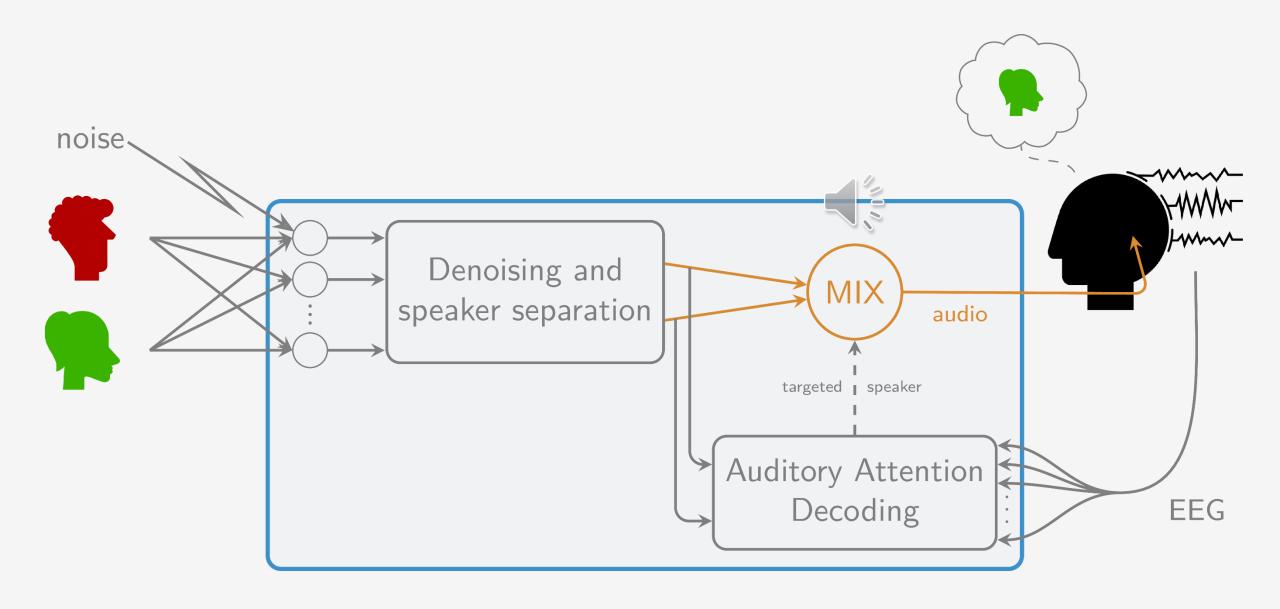


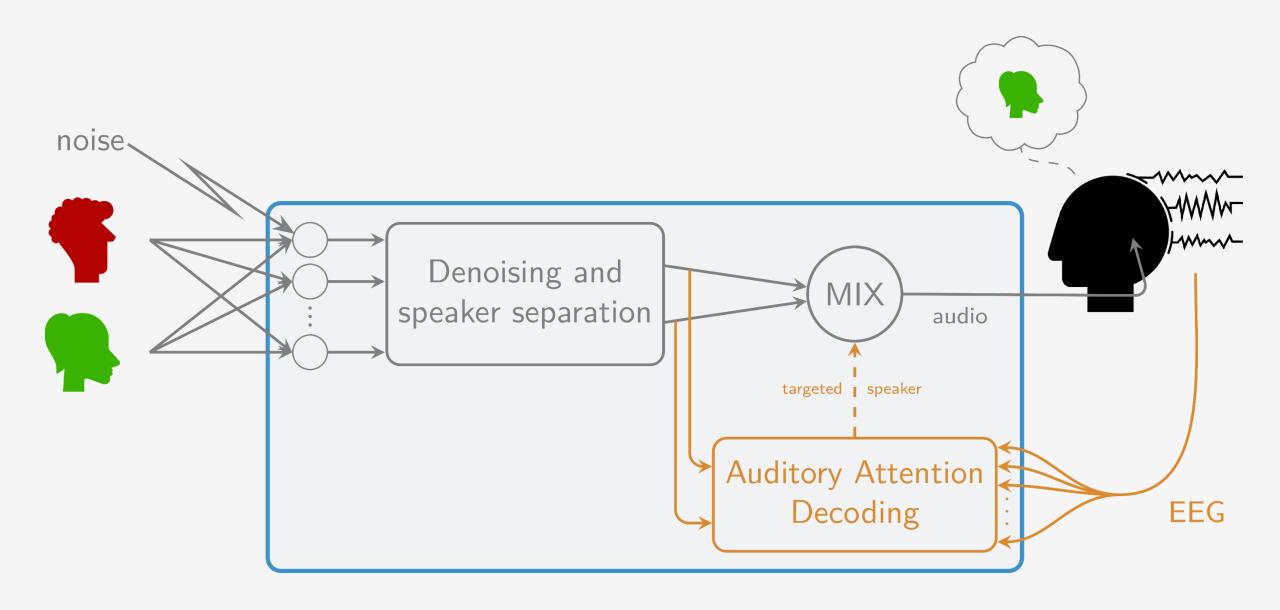


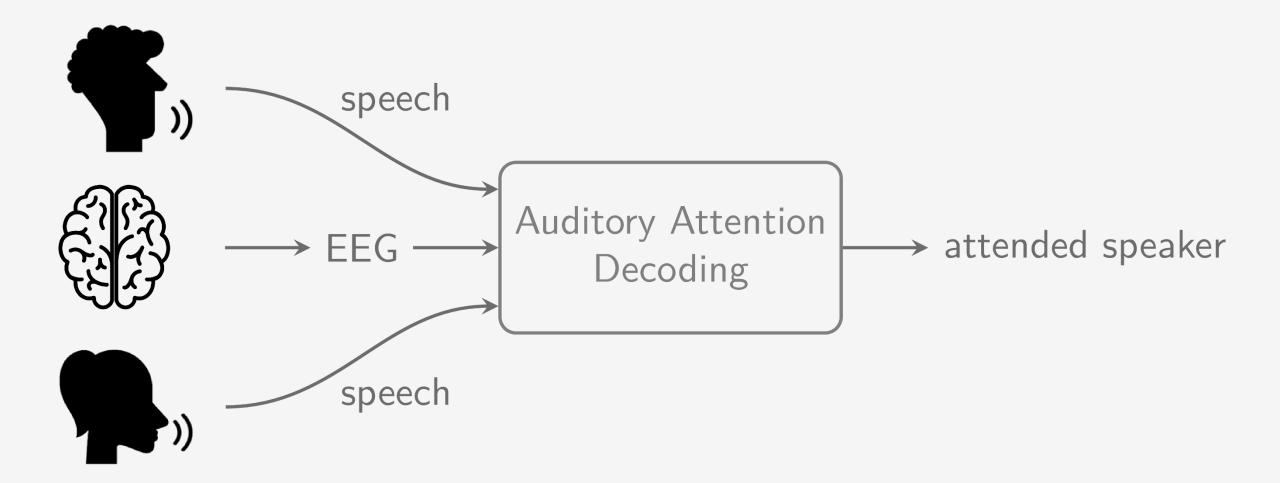
**Smart neuro-steered hearing device** 



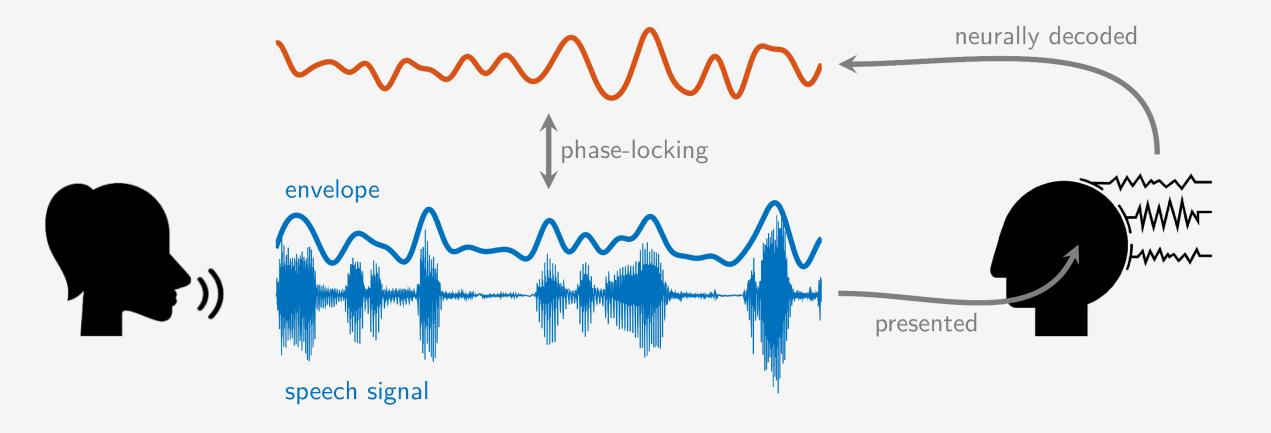


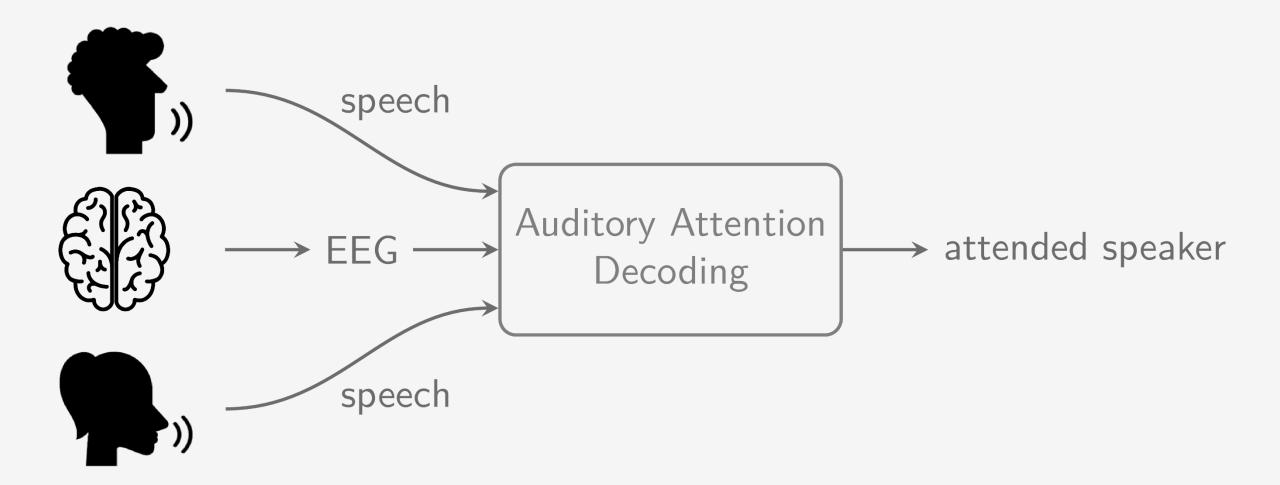


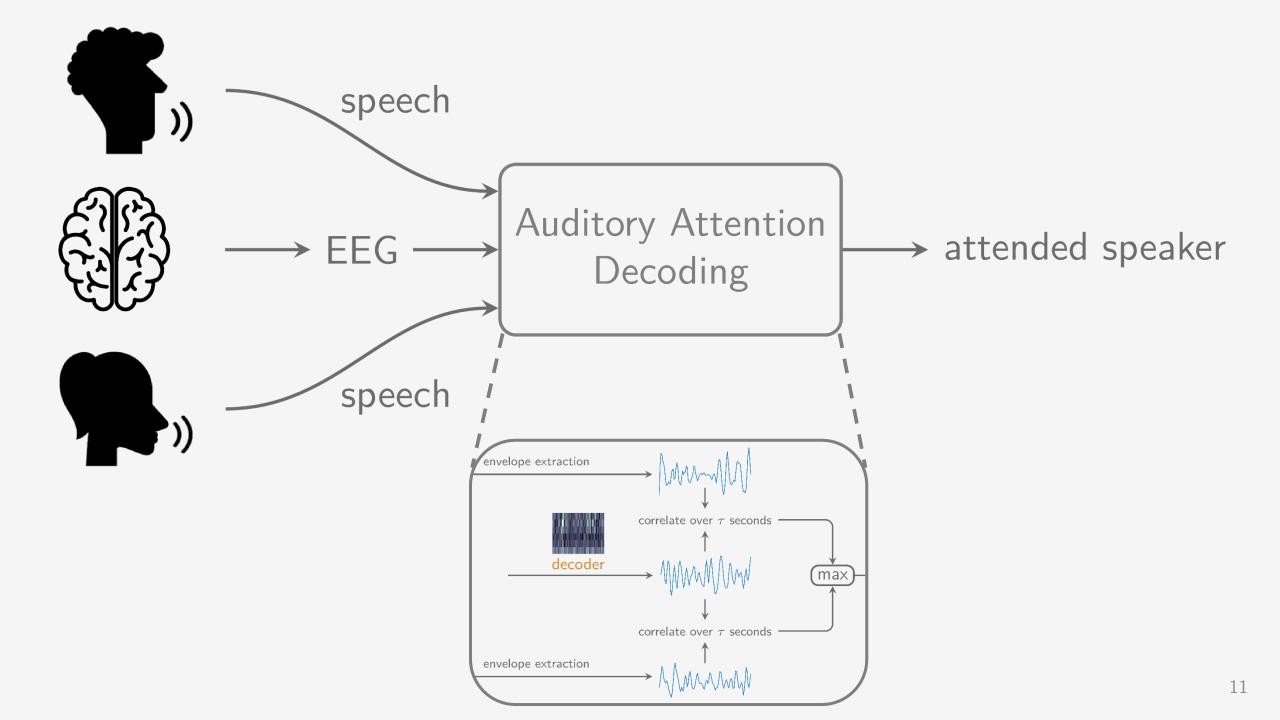




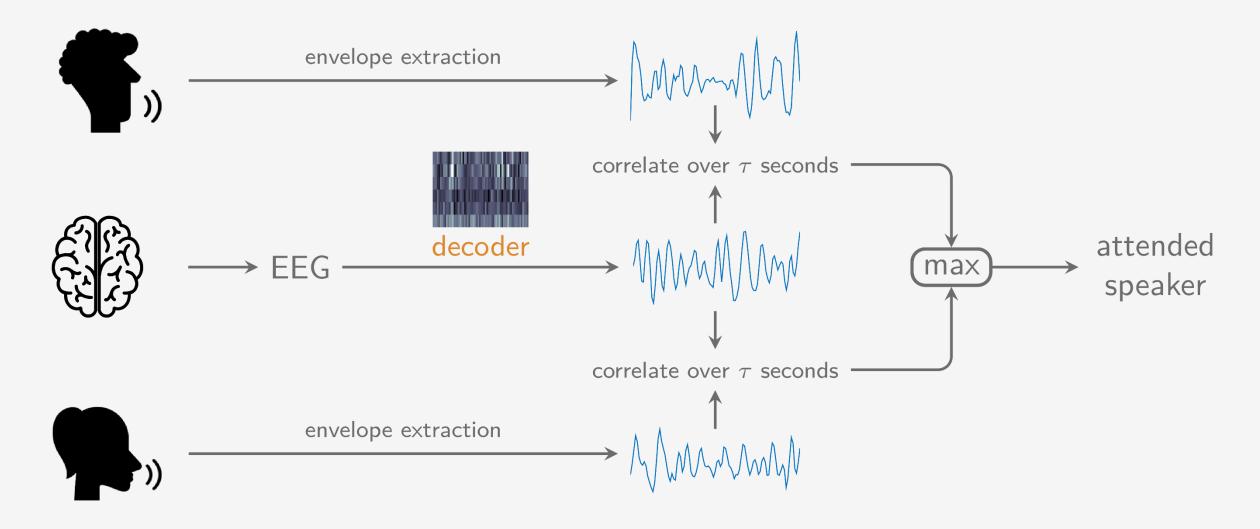
# **Neural tracking of speech**



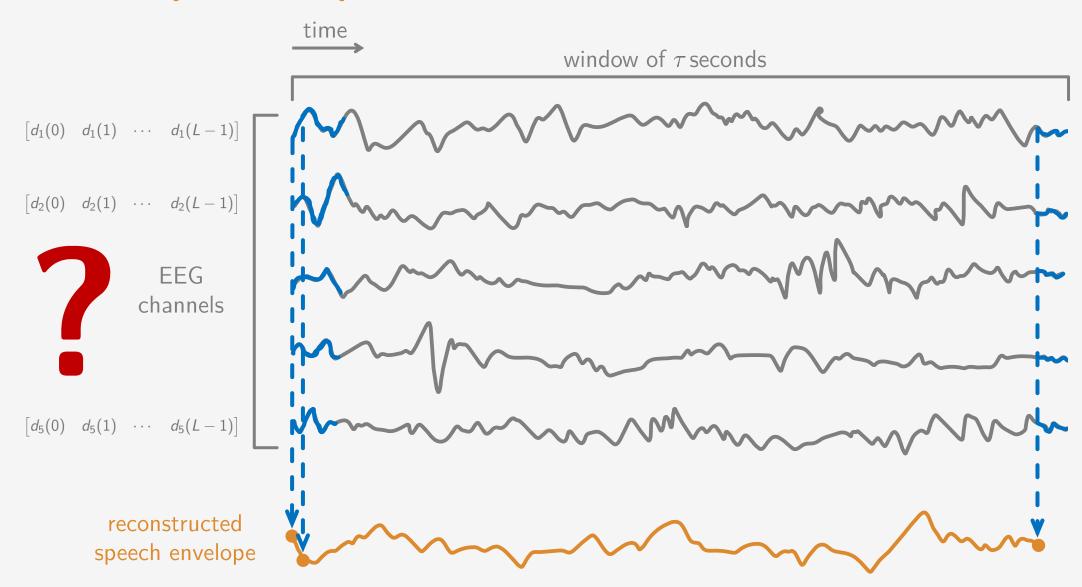




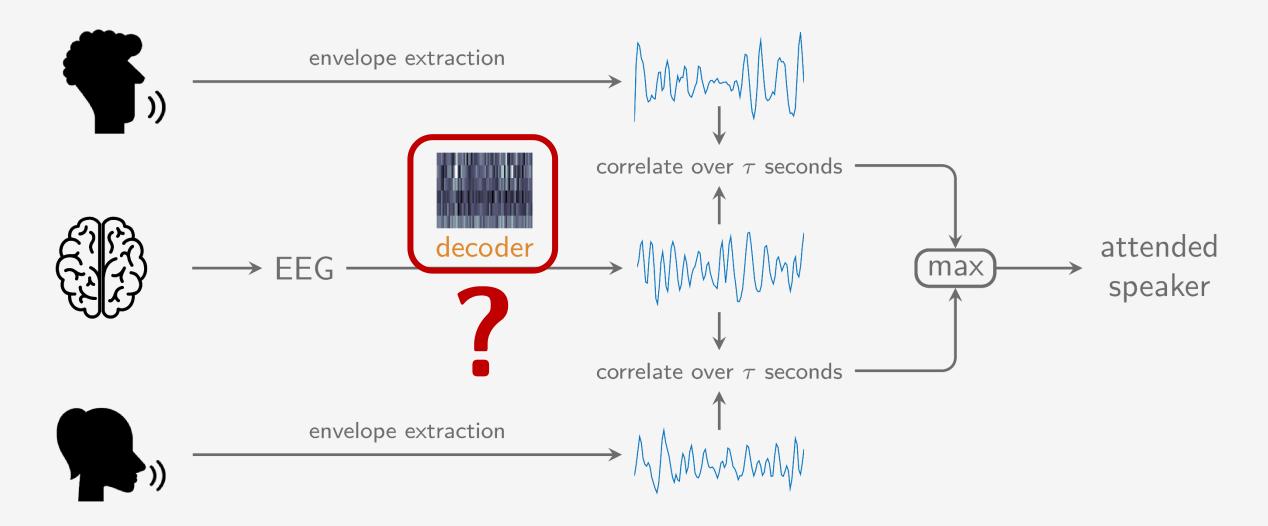
#### **Stimulus reconstruction**



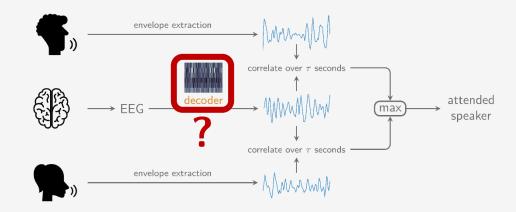
## Linear spatio-temporal decoder

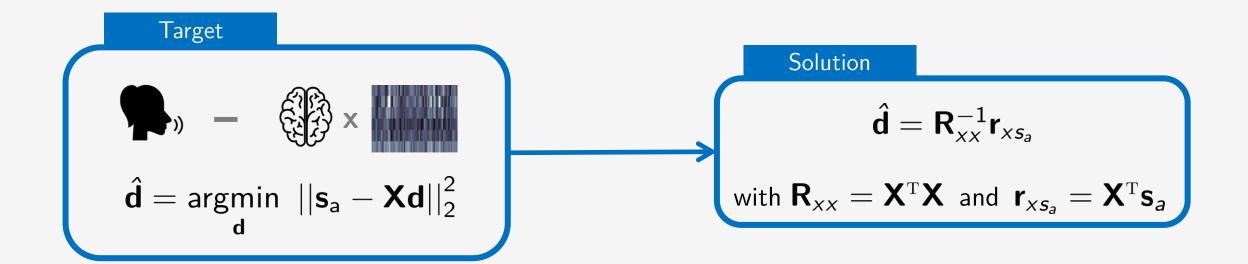


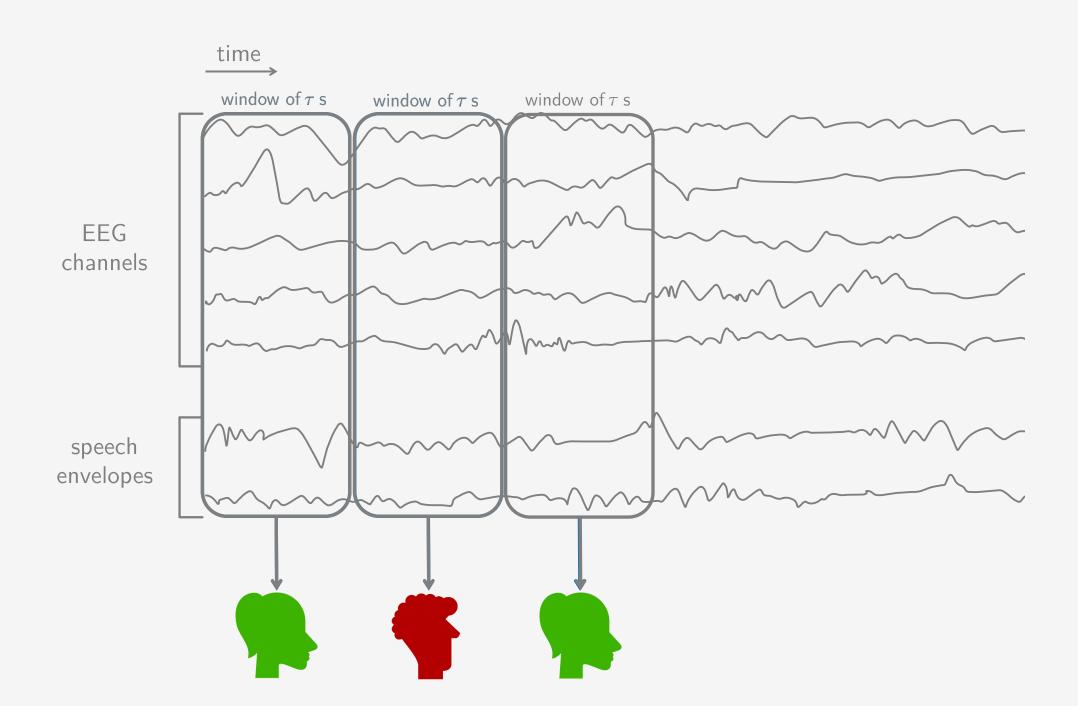
#### Stimulus reconstruction – backward decoding



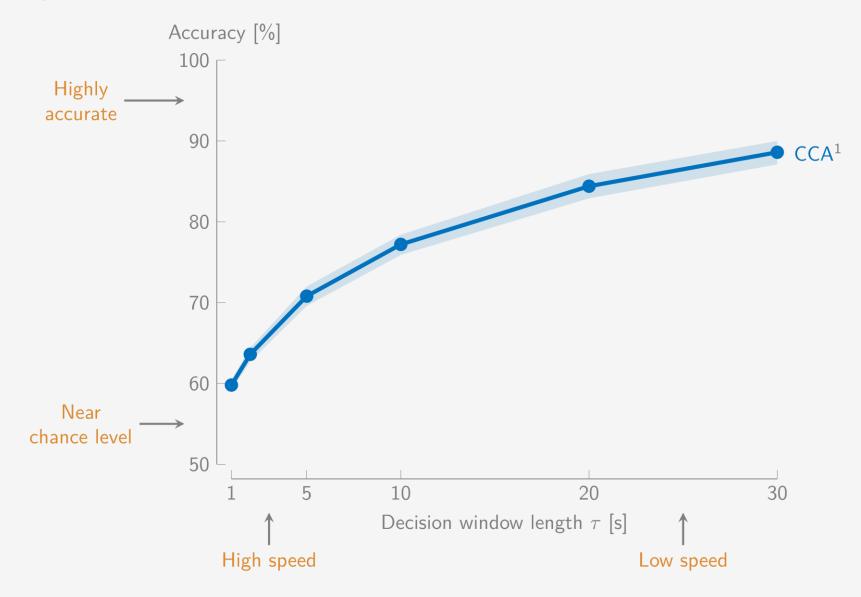
#### **Least-squares decoding**

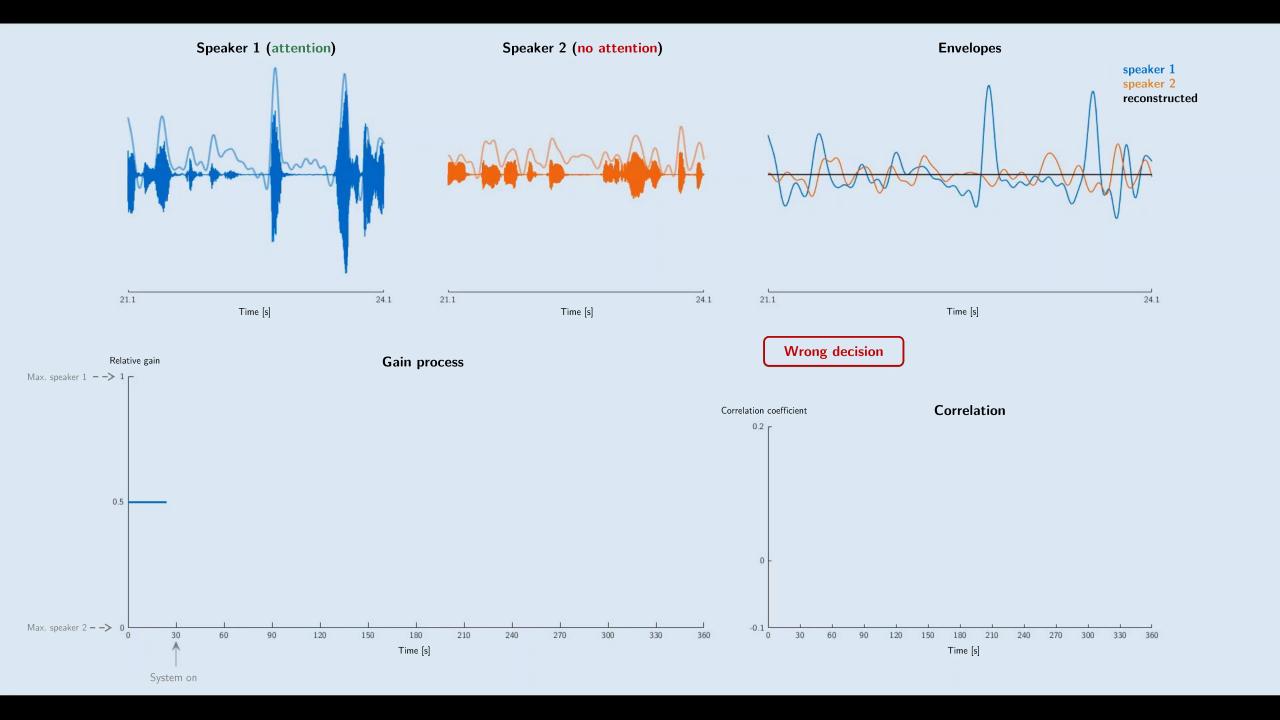






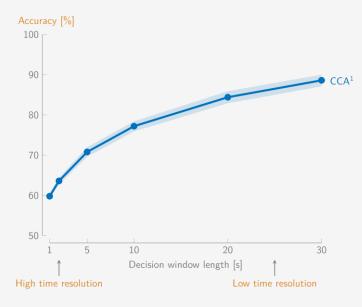
### Accuracy-speed tradeoff for stimulus reconstruction







1. Low signal-to-noise ratio leads to accuracy-speed tradeoff





2. Existing AAD algorithms need to be pre-trained offline in a supervised manner, and are fixed during operation



3. Existing AAD algorithms rely on the availability of clean speech signal envelopes

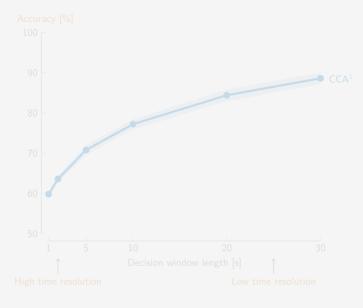


4. Existing AAD algorithms often assume bulky, non-wearable EEG setups





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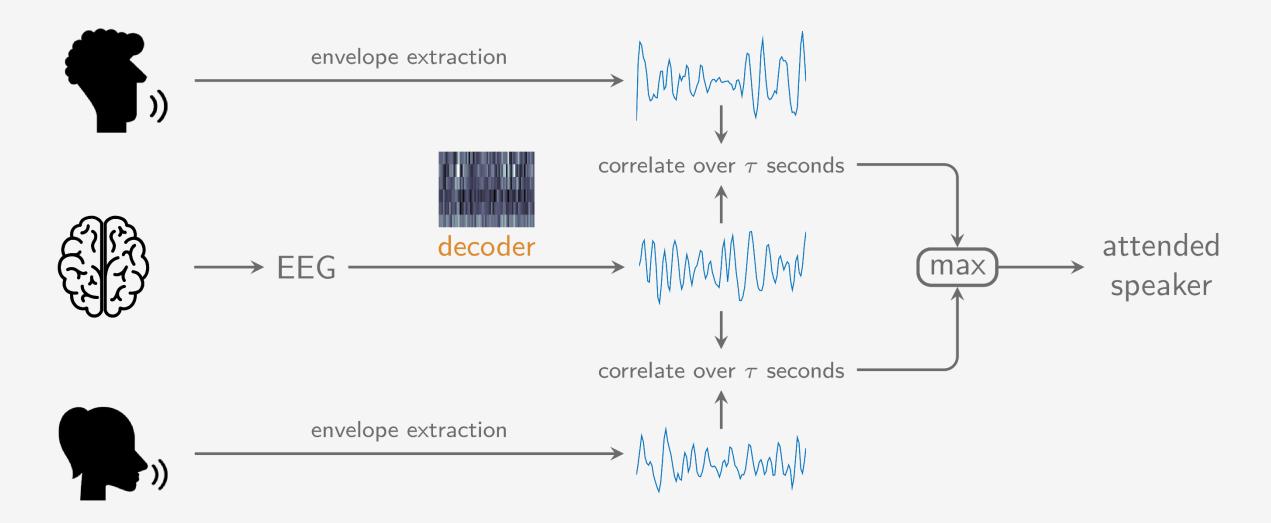


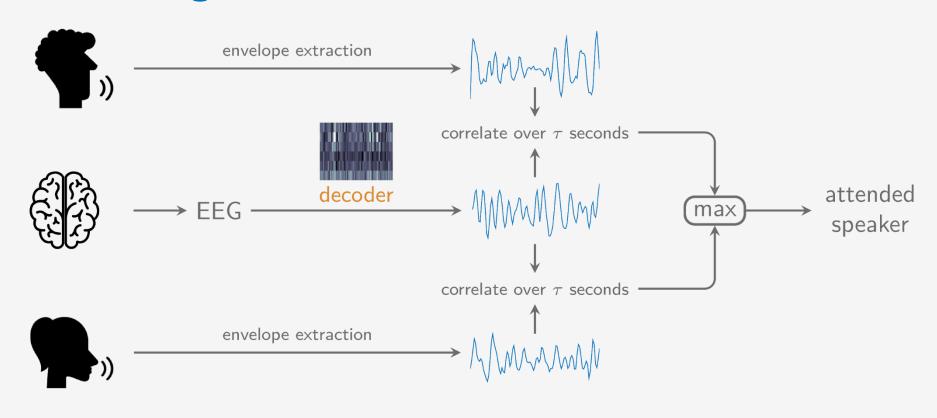
Existing AAD algorithms often assume bulky, non-wearable EEG setups



Existing AAD algorithms need to be pre-trained offline in a supervised manner, and are fixed during operation

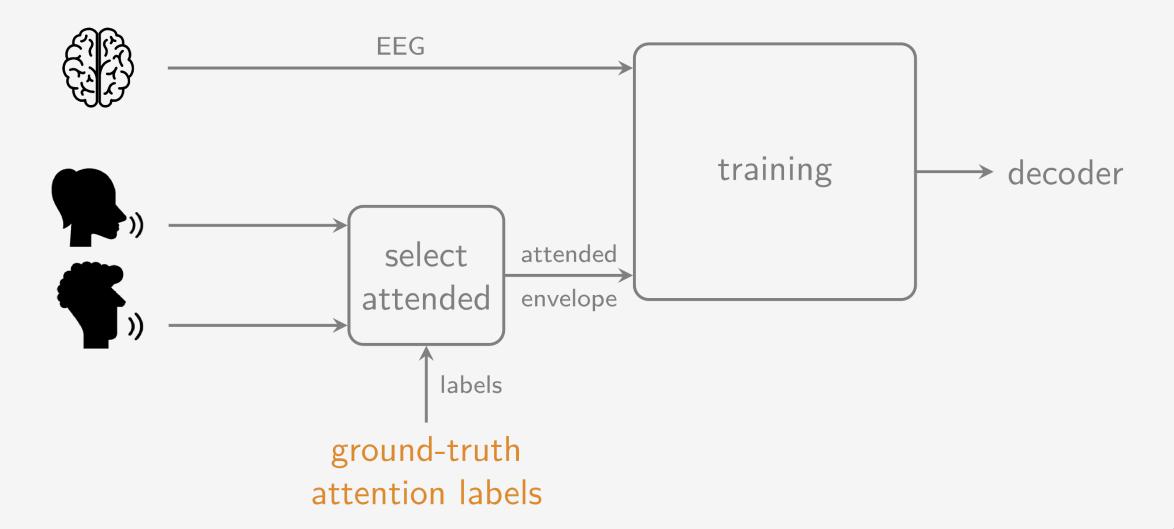






#### Least-squares decoder

$$\hat{f d} = {f R}_{xx}^{-1} {f r}_{xs_a}$$
 with  ${f R}_{xx} = {f X}^{ ext{T}} {f X}$  and  ${f r}_{xs_a} = {f X}^{ ext{T}} {f s}_a$ 

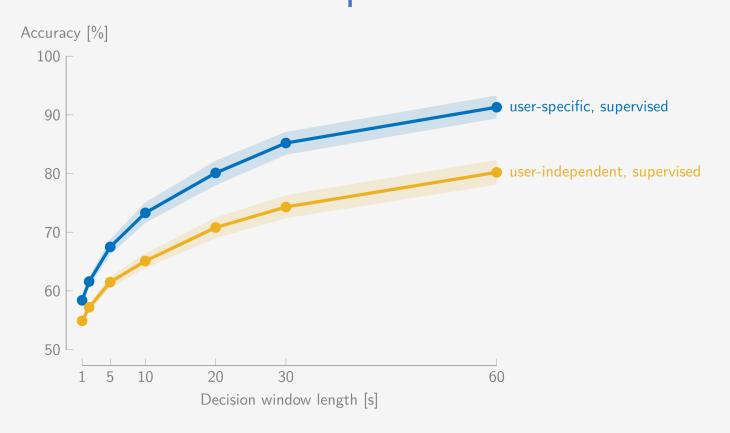


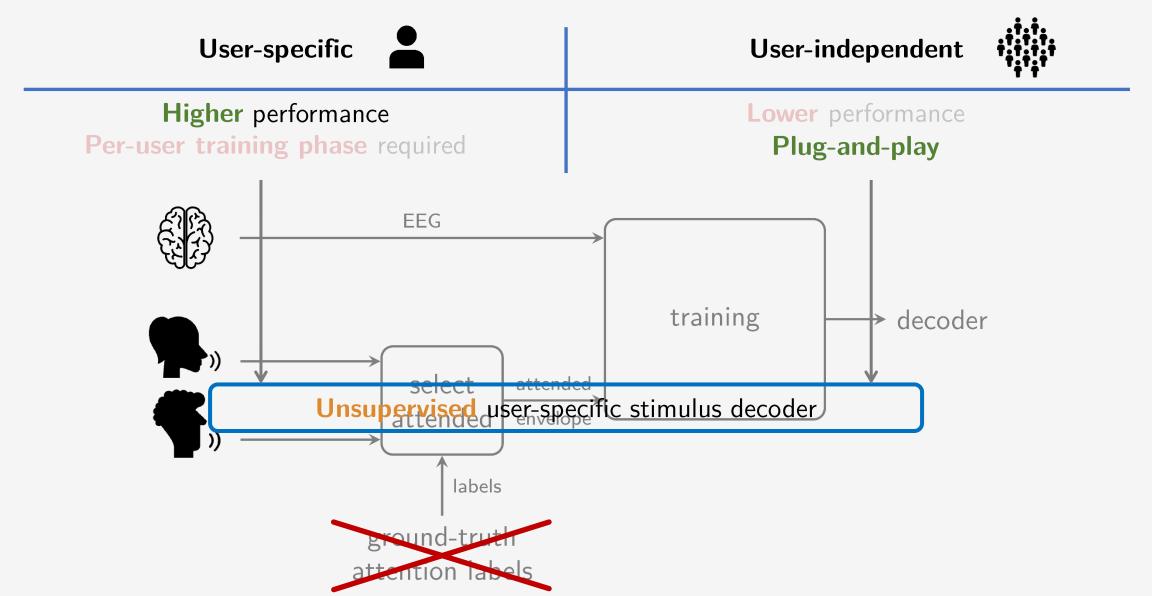
User-specific User-independent

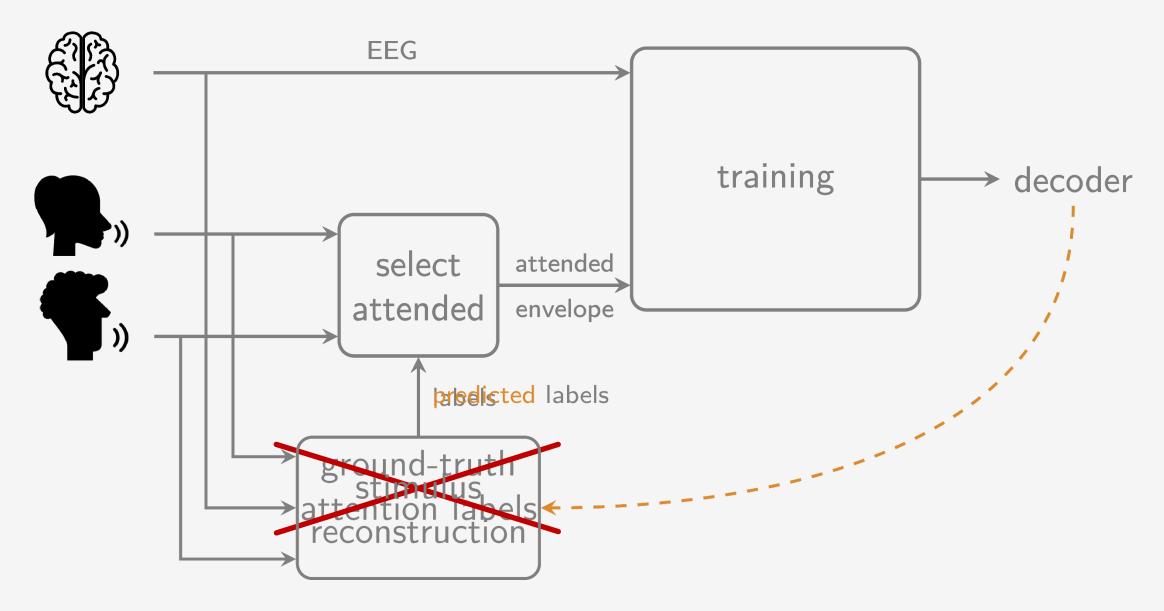
Higher performance
Per-user training phase required

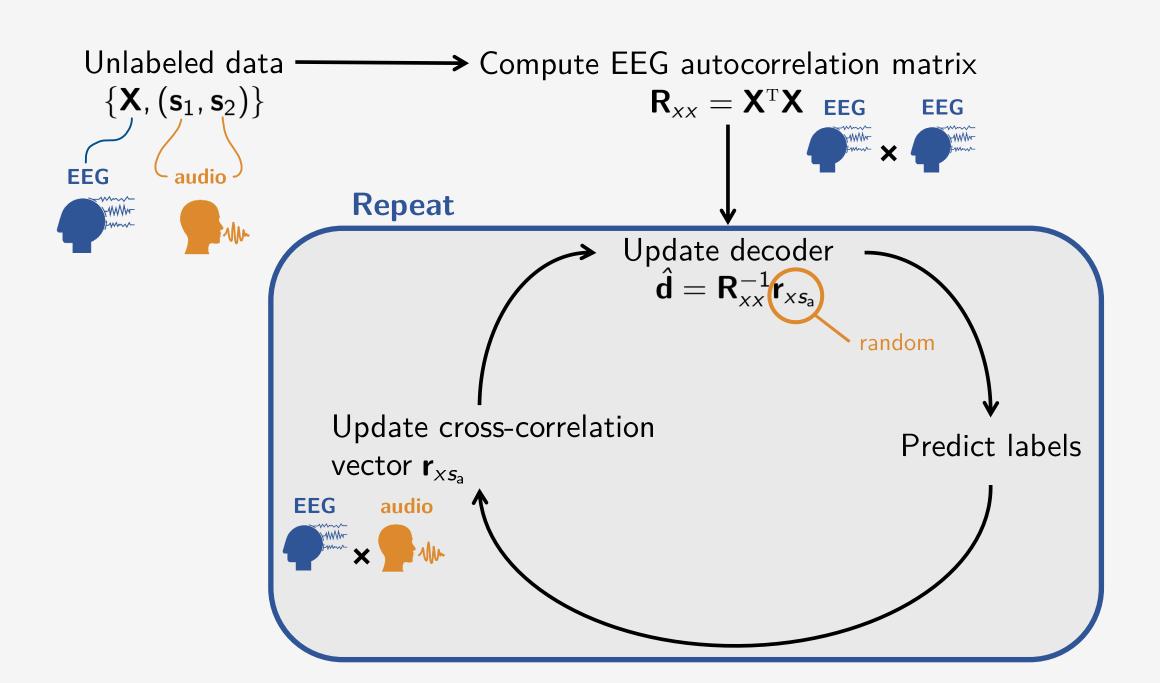
User-independent

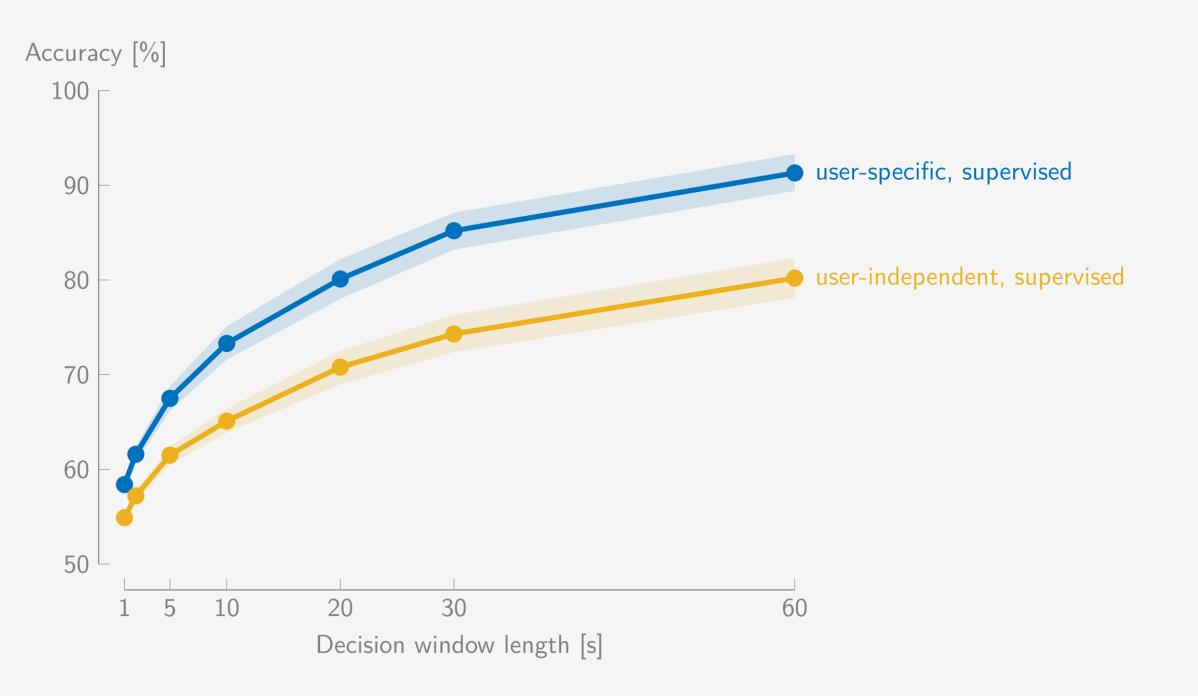
Lower performance
Plug-and-play

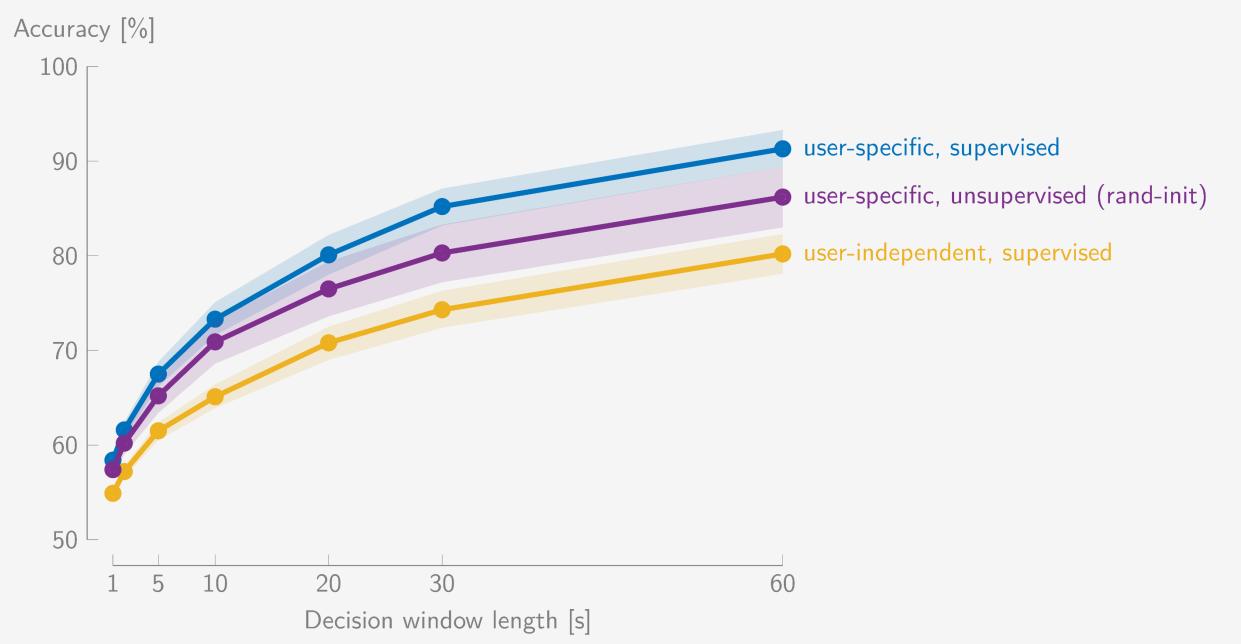




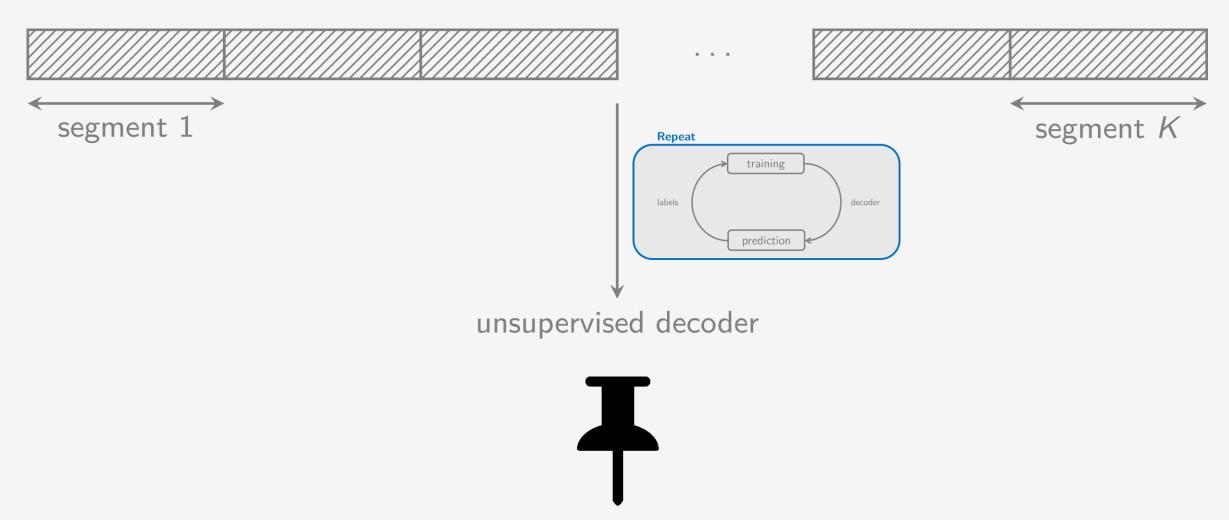




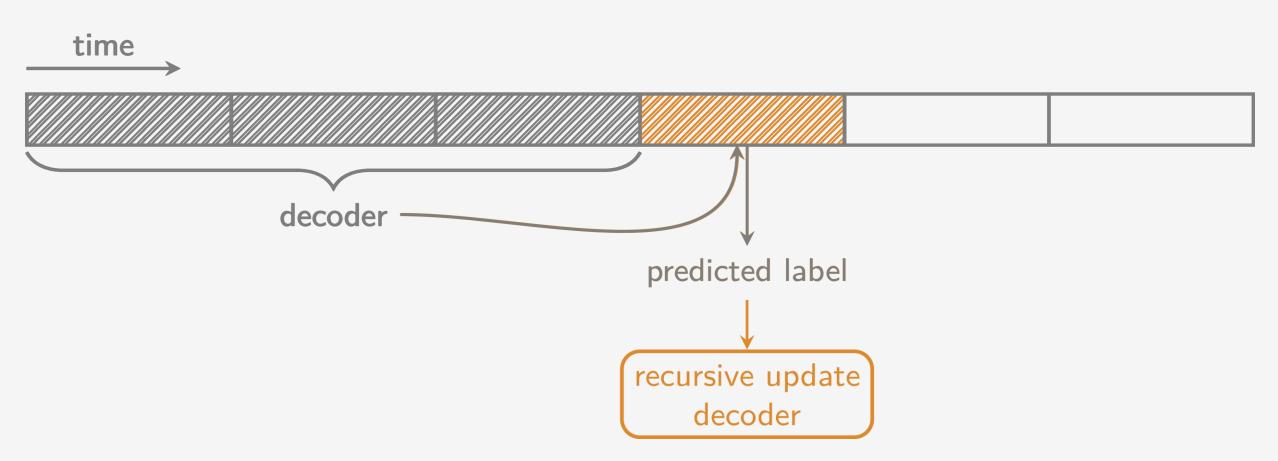


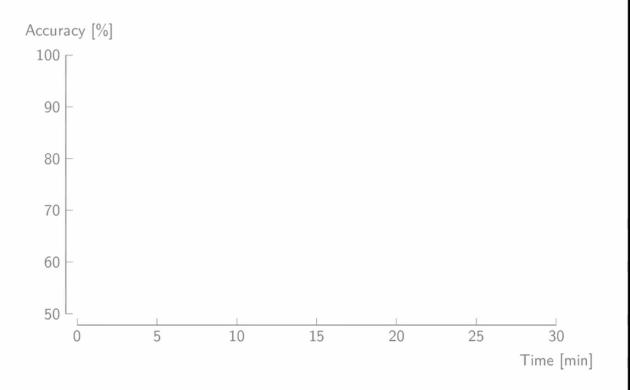


### Unsupervised stimulus decoder is still fixed

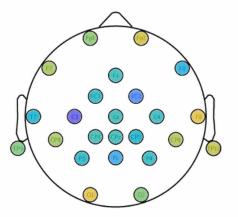


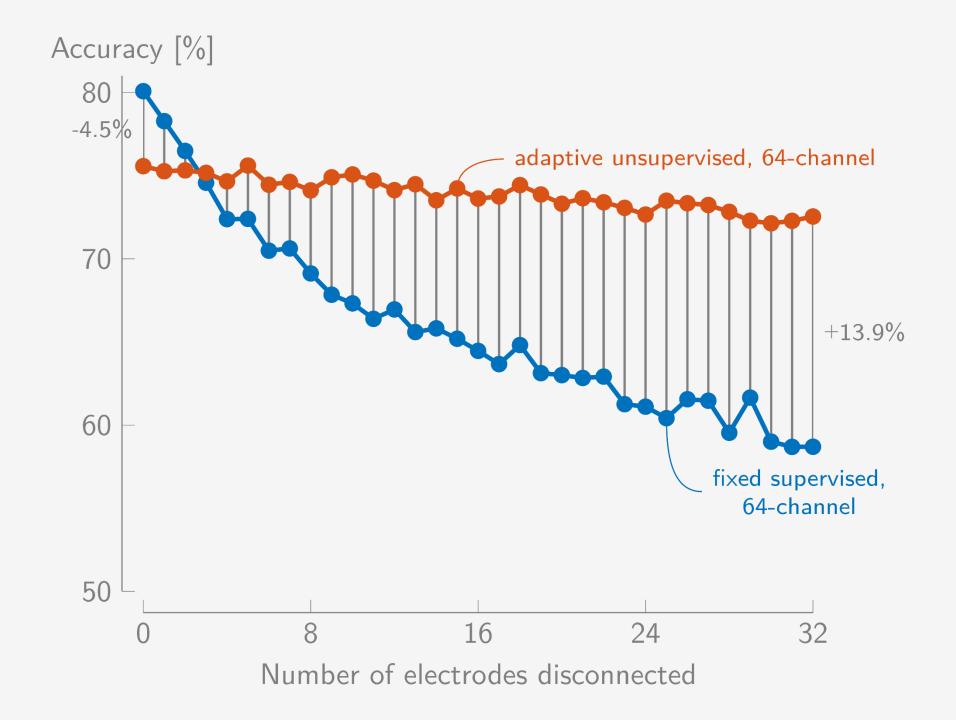
### Time-adaptive unsupervised stimulus reconstruction decoding

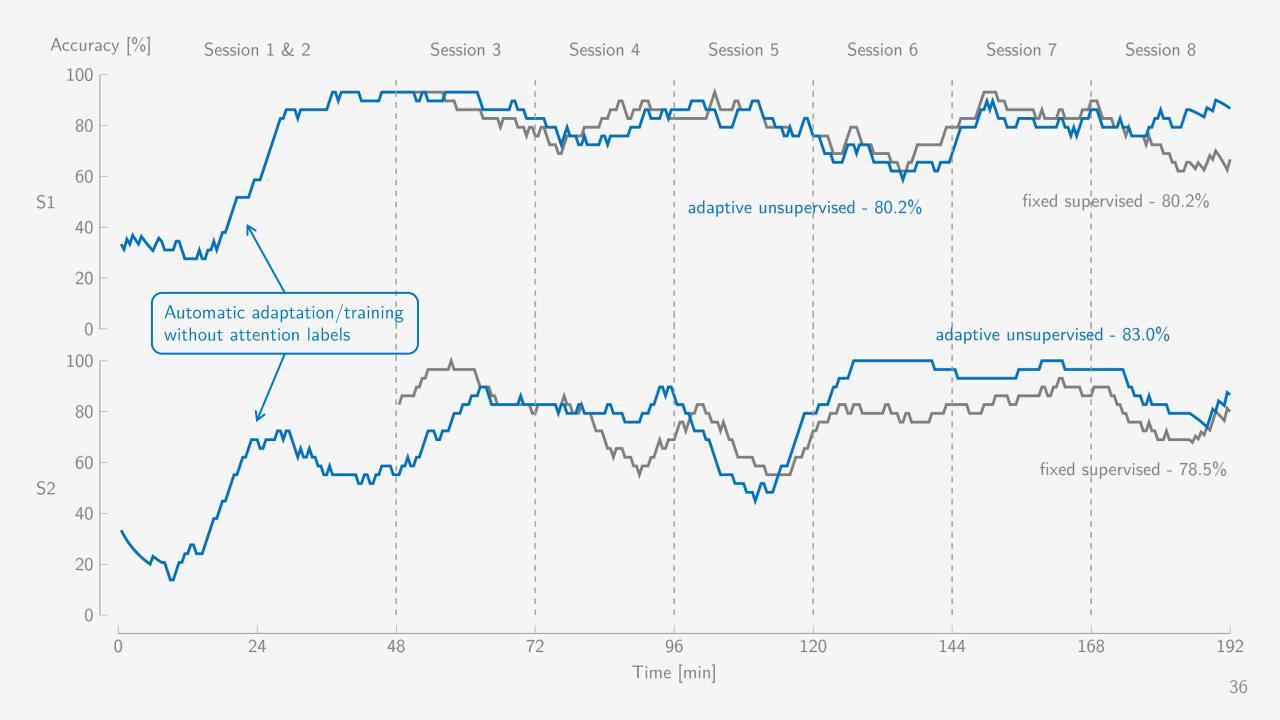




#### Fixed supervised decoder









Existing AAD algorithms need to be pre-trained offline in a supervised manner, and are fixed during operation





Existing AAD algorithms often assume bulky, non-wearable EEG setups



Existing AAD algorithms need to be pre-trained offline in a supervised manner, and are fixed during operation





Existing AAD algorithms often assume bulky, non-wearable EEG setups

#### **EEG** in real life?

#### Wireless EEG headset





Cognionics

mBrainTrain

#### Miniaturized EEG



Record from CI electrode



In-ear EEG Kidmose et al. (2013)



Pasted EEG module Lehmkuhle et al. (2015)



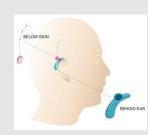
Around-the-ear EEG ('cEEGrid') Mirkovic et al. (2016)



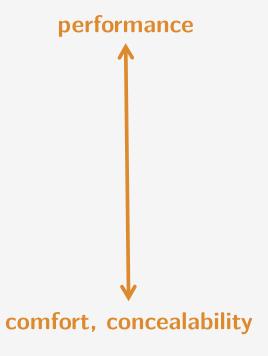
Seize-IT device



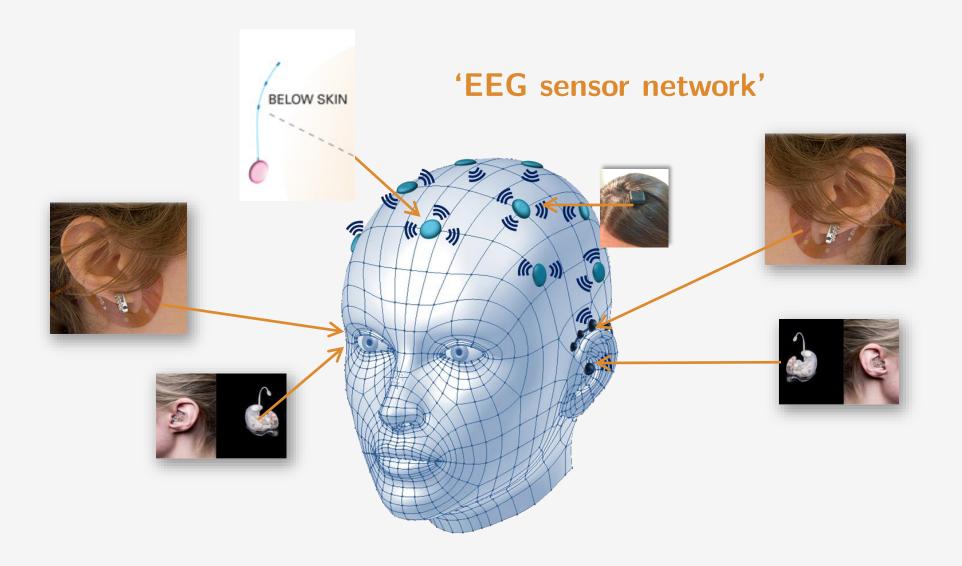
Printable e-skin Rogers et al. (2011)



Subcutaneously Juhl et al. (2010)

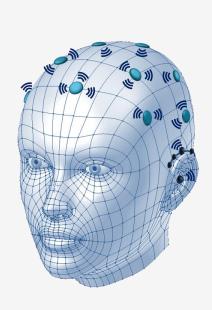


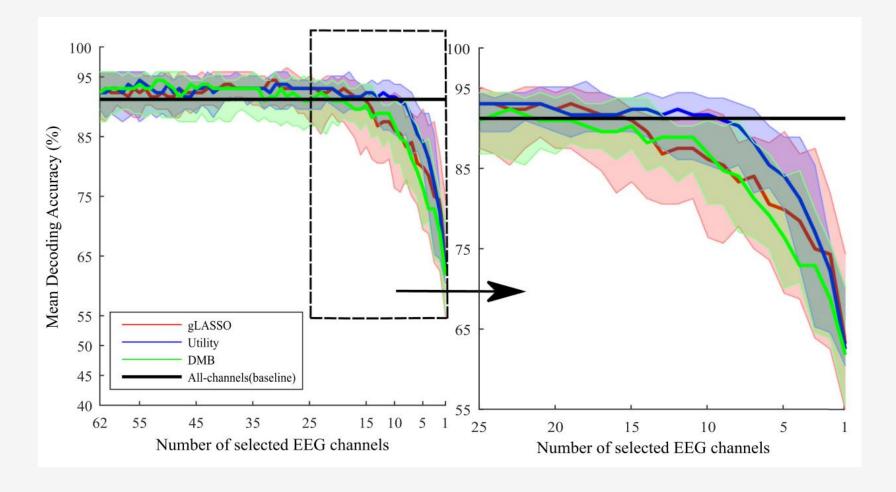
#### Combine multiple miniature EEG nodes at various positions



#### **Top-down: EEG channel selection**

Free placement: 64 channels  $\rightarrow$  ~8 channels without performance decrease





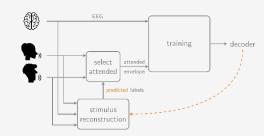


Existing AAD algorithms need to be pre-trained offline in a supervised manner, and are fixed during operation





Existing AAD algorithms often assume bulky, non-wearable EEG setups



A time-adaptive unsupervised stimulus reconstruction algorithm

**Solution** 



Towards integrated in-ear and around-the-ear EEG